

IOLBOX

AN IOLINK SLAVE
DEVICE
AND MODBUS RTU
GATEWAY FOR
MECHATRONIC
GRIPPERS



A unique design for several products



IO-LINK INTERFACE

Using the IO-Link technology the IOLINK master communicates with **IOLBOX** sharing both process data and parameters.

Process Data

- Actuator commands (opening, closing, braking, etc...)
- Force reference value (gripping force limitation)

Parameters

- Actuator status (fully opened, fully closed, object gripped, error, etc...)
- Position of the jaws

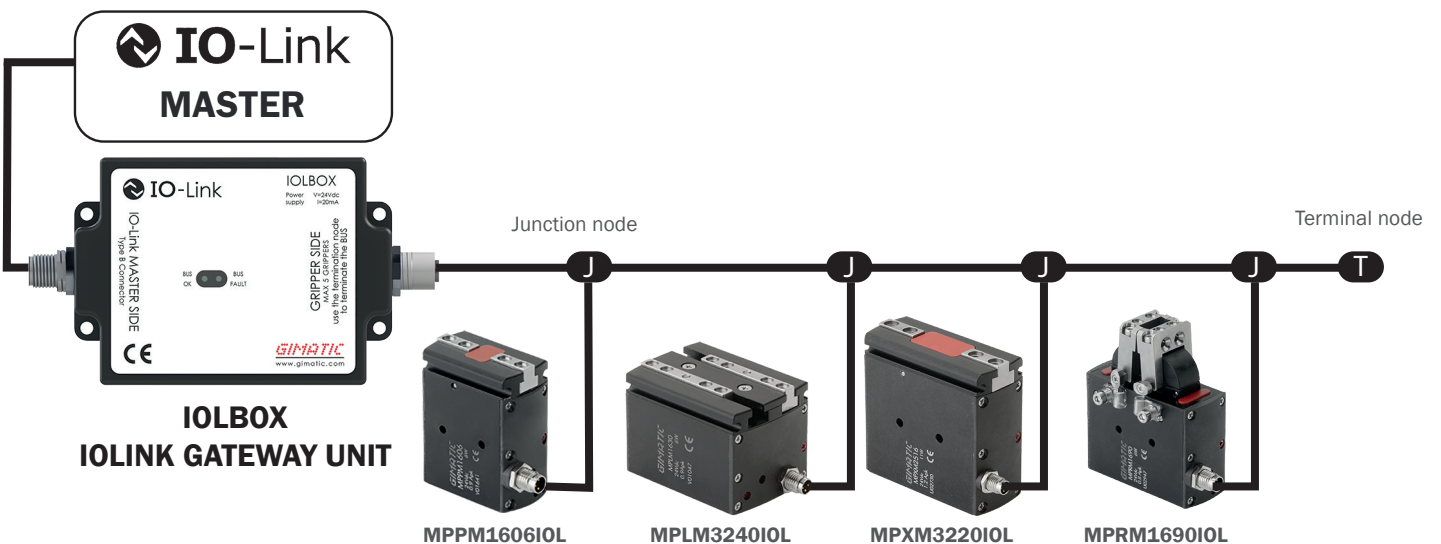
- > Up to 5 grippers.
- > Simple installation and configuration of the device.
- > Monitoring of the status of the device.
- > Advanced diagnosis functionalities.
- > Easily replace a device with another of the same type.
- > Suitable for all gripper sizes (16, 25, 32).
- > No electricity consumption when engaged.
- > 10 milion cycle maintenance-free.
- > Position retention guaranteed in event of blackout.
- > Modbus RTU over RS-485 gateway.
- > Force and position controlled cyclically.
- > Exchanged parameters with data and maintenance information.
- > Slave ID settable to create the grippers network.



Network of grippers: several different Plug & Play grippers can be connected to the same IOLBOX

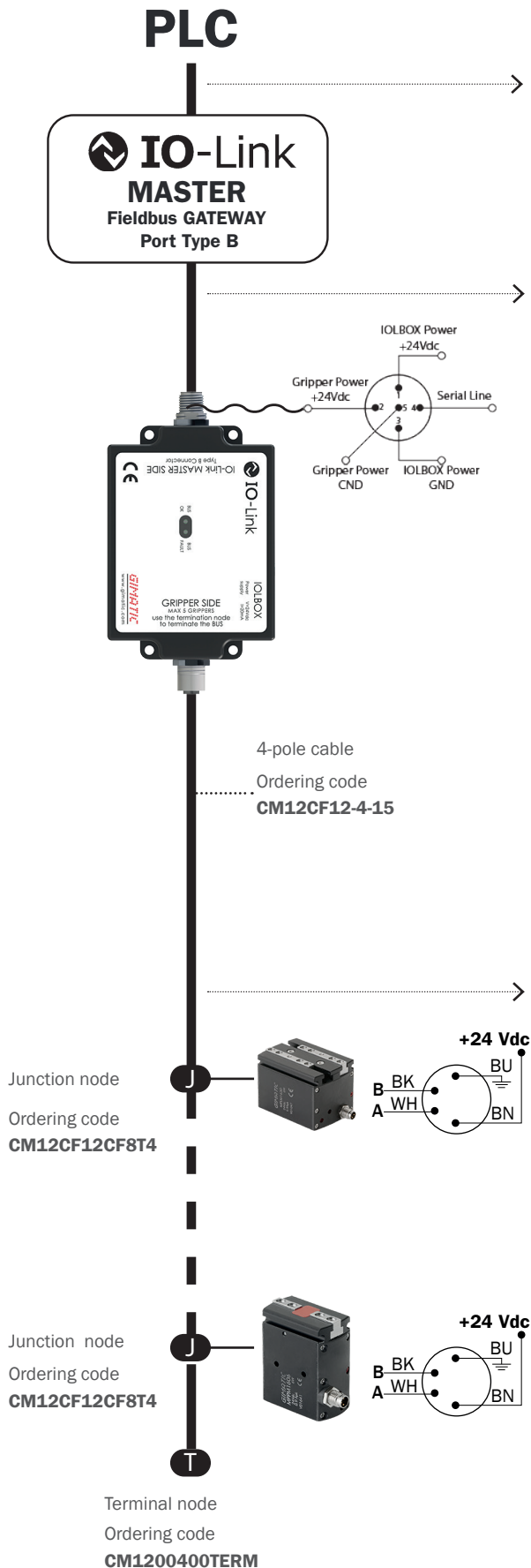
The user can create a network of grippers where the **IOLBOX** is the unique IO-Link device that uses only one node of the external IO-Link master.

The **IOLBOX** behaves as an IO-Link gateway toward a special digital version of Gimatic's standard electric grippers.



All Gimatic grippers can be ordered in IO-LINK version by adding 'IOL' to the normal code.

Architecture example



Fieldbus: Ethernet, Profibus, Profinet, ecc...

IO-Link Protocol

Data Exchanged (for each gripper)

Cyclic Data Input

- Open/ Close
- Force (%)

Cyclic Data Output

- Virtual Proximity Switch Position
- Jaws stroke (0.1mm resolution)

Acyclic Parameters

- Slave ID*
- Code
- Batch
- Serial Number
- Firmware Edition
- Max Force (N)
- Device Stroke (0.1mm resolution)
- Mass (g)
- Max Frequency (0.1 Hz)
- Number of Cycles Performed

* The slave ID is the identifier for each gripper. All the grippers receive the messages from the IOLBOX but only the one with the same slave ID will respond/execute the command. It must be set during installation, but it can still be modified for any need.

RS-485 Modbus

- Baud Rate 9600.
- Differential A and B Channel.
- IOLBOX sends the cyclic data to each gripper cyclically, using the various Slave ID according to the grippers connected.
- The time to handle five grippers is about 400ms.
- Acyclic Parameters were read at time of the gripper connection.



Catalogue



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